

## TOTAL CURVATURE IN MINKOWSKI PLANES

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### Abstract

Generalization of the following result in Euclidean and Minkowski spaces is given. A closed curve of class  $C^2$  in Euclidean  $n$ -space which lie in a ball of radius  $R$  satisfies the inequality  $L \leq RK$  where  $L$  is the length of the curve and  $K$  is its total curvature.

### 1. Introduction

Let  $C$  be a closed curve of class  $C^2$  in Euclidean  $n$ -space  $\mathbf{R}^n$ . We write the equation of  $C$  as  $x = x(s)$ ,  $0 \leq s \leq L(C)$ , where  $s$  denotes Euclidean arc length and  $L(C)$  is the Euclidean length of  $C$ . Denoting differentiation with respect to  $s$  by a dot, we define the total curvature of  $C$  as

$$(1) \quad K(C) = \int_C |\ddot{x}| ds = \int_0^L |\kappa(s)| ds,$$

where  $\kappa(s)$  denotes the Euclidean curvature parameterized by  $s$ . Chakerian [2,3] prove that if  $C$  is constrained to lie in a ball of radius  $R$  then

$$(2) \quad L(C) \leq RK(C).$$

The curves for which equality holds in (2) are circles of radius  $R$  traversed a certain number of times.

In this article we prove the following theorem concerning the  $p^{\text{th}}$  mean of curvature in Euclidean spaces and consider generalizations of (2) for a closed curve  $C$  in a Minkowski plane (Minkowski spaces are simply finite dimensional normed linear spaces).

**Theorem 1** *Let  $C$  be a closed curve of class  $C^2$  in Euclidean  $n$ -space  $\mathbf{R}^n$ . Let  $\kappa(s)$  and  $K(C)$  denote the curvature and the total curvature of  $C$  respectively. Let  $L(C)$  denote the length of  $C$ . Assume  $P \geq 1$  and that  $C$  is constrained to lie in a ball of radius  $R$ . Then*

$$(3) \quad \left( \int_0^L |\kappa(s)|^P ds \right)^{\frac{1}{P}} \geq \frac{L^{\frac{1}{P}}}{R}.$$

curves for which equality holds are circles of radius  $R$  traversed a certain number of times.

Preliminary definitions and concepts are discussed in section 2. The proof of Theorem 1 and related results are given in section 3.

## 2. Preliminaries

By a plane convex body we shall mean a compact, convex subset of the Euclidean plane having a non-empty interior. We shall take a "unit circle"  $E$  for a Minkowski plane to be a centrally symmetric convex body with its center at the origin in the Euclidean plane. The Minkowski distance defined by  $E$  from  $x$  to  $y$  is given by

$$(4) \quad \|x - y\|_E = \frac{\|x - y\|_e}{r}$$

where  $\|x - y\|_e$  is the Euclidean distance from  $x$  to  $y$  and  $r$  is the Euclidean radius of  $E$  in the direction of the vector  $y - x$ . An equivalent definition of Minkowski length is given in [6, p17] by  $\|x\|_E = \inf\{\lambda \in \mathbf{R}^+ : x \in \lambda E\}$ .

Below we review the definition of the distance function of a convex body  $K$  and use the definition to obtain the formula in (4). Let  $K$  be a convex body in  $\mathbf{R}^n$  containing the origin as an interior point. The distance function of  $K$ ,  $F(K, x)$ , is defined by

$$(5) \quad F(K, x) = \inf\{\lambda > 0 : x \in \lambda K\}, x \in \mathbf{R}^n.$$

For a convex body  $K$ , the radial function of  $K$  in the direction of a unit vector  $u$  is defined by

$$(6) \quad r(K, u) = \frac{1}{F(K, u)}$$

Equation (6) and the homogeneity of the distance function imply

$$(7) \quad F(K, x) = F(K, \|x\|_e u) = \|x\|_e F(K, u) = \frac{\|x\|_e}{r(K, u)}$$

where  $\|x\|_e$  is the usual Euclidean norm and  $u = \frac{x}{\|x\|_e}$  for  $x \neq 0$  and  $\|0\| = 0$ . Let  $E$  be a centrally symmetric convex body centered at the origin. For each  $u \in S^{n-1}$ , let  $r(E, u)$  be the radius of  $E$  in the direction  $u$ .

**Theorem 2** Let  $E$  be a centrally symmetric convex body in  $\mathbf{R}^n$ . Define the distance function of  $E$  as in (5). Let  $F(x) = F(K, x)$ . Then  $\|\cdot\| = F(\cdot) = \frac{\|x\|_e}{r(K, u)}$  is a norm.

**Proof.** (i)  $F(x) = 0$  if and only if  $x = 0$  is clear.

(ii) If  $\lambda > 0$  then  $F(\lambda x) = \inf\{\mu > 0 : \frac{\lambda x}{\mu} \in E\} = \lambda \inf\{\mu > 0 : \frac{x}{\mu} \in E\} = \lambda F(x) = |\lambda| F(x)$ .

If  $\lambda < 0$  then  $F(\lambda x) = F((- \lambda)(-x)) = (- \lambda) F(-x) = |\lambda| F(x)$  where  $F(-x) = F(x)$  follows from the fact that  $E$  is symmetric.

(iii) Since  $\frac{x}{F(x)} \in E$  and  $\frac{y}{F(y)} \in E$ , by the convexity of  $E$  we have  $\frac{F(x)}{F(x) + F(y)}$ .

$$(8) \quad \frac{x}{F(x)} + \frac{F(y)}{F(x) + F(y)} \cdot \frac{y}{F(y)} \in E. \text{ Hence } \frac{x + y}{F(x) + F(y)} \in E.$$

$$F(x + y) = \inf\{\lambda > 0 : \frac{x + y}{\lambda} \in E\} \leq F(x) + F(y)$$

Assuming that the boundary of the unit circle  $E$  has nowhere zero Euclidean curvature, we define the Minkowskian curvature of a curve  $C$  at a point  $P$  by

$$(9) \quad \kappa_m(C, P) = \frac{\kappa_e(C, P)}{\kappa_e(E, P)}$$

where  $\kappa_e(C, P)$  and  $\kappa_e(E, \bar{P})$  denote the Euclidean curvature of  $C$  and  $E$  at points  $P$  and  $\bar{P}$  respectively, such that the unit tangent to  $C$  at  $P$  is parallel to the unit tangent to  $E$  at  $\bar{P}$ . If there are two different points  $\bar{P}$  and  $\hat{P}$  of  $E$  with parallel tangents to the tangent to  $C$  at  $P$ , then using the fact that  $E$  is centrally symmetric, it follows that  $\kappa_e(E, \bar{P}) = \kappa_e(E, \hat{P})$ . Note that if we use the parametrization  $\Theta$  for  $E$  where  $\Theta$  is the angle that the tangent to  $E$  makes with the horizontal, then  $\kappa_e(E, \Theta) = \kappa_e(E, \Theta + \pi)$  because of the fact that  $E$  is centrally symmetric.

Other works define Minkowskian curvature differently. See for example Busemann [1]. Our definition permits us to give a generalization of Theorem 1. Note that in the Euclidean case  $\kappa_e(E, ) = 1$  and the Minkowskian curvature is the same as the usual Euclidean curvature. In order to define the Minkowskian length of a curve, we need the following concepts, which can be found in Conway [4, p.58].

A function  $\gamma : [a, b] \rightarrow \mathbf{R}^n$  is of bounded variation on  $[a, b]$  with respect to the norm  $\|\cdot\|$  if and only if there is a constant  $M > 0$  such that for any partition

$P = \{a = t_0 < t_1 < t_2 < \dots < t_n = b\}$  of  $[a, b]$ , the total variation of  $\gamma$  over  $[a, b]$  satisfies

$$(10) \quad V(\gamma, P) = \sum_1^n \|\gamma(t_k) - \gamma(t_{k-1})\| \leq M.$$

**Theorem 3** *A function  $\gamma : [a, b] \rightarrow \mathbf{R}^n$  is of bounded variation with respect to the Euclidean norm  $\|\cdot\|_e$  if and only if it is of bounded variation with respect to the Minkowskian norm  $\|\cdot\|$ .*

**Proof.** Let  $R_1$  and  $R_2$  be the minimum and maximum radii of the unit ball  $E$  measured in the Euclidean norm. Let  $P = \{a = t_0 < t_1 < t_2 < \dots < t_n = b\}$  be a partition of  $[a, b]$ . Let  $V_e(\gamma, P)$  and  $V_m(\gamma, P)$  denote the total variations with respect to the Euclidean and Minkowskian norms, respectively, and let  $u_k$  be a unit vector in the direction of  $\gamma(t_k) - \gamma(t_{k-1})$ .

Suppose  $\gamma$  is of bounded variation with respect to the Euclidean norm. We can find a bound for  $V_m(\gamma, P)$  as follows:

$$(11) \quad V_m(\gamma, P) = \sum_1^n \|\gamma(t_k) - \gamma(t_{k-1})\| = \sum_1^n \frac{\|\gamma(t_k) - \gamma(t_{k-1})\|_e}{r(E, u_k)} \leq \frac{V_e(\gamma, P)}{R_1}$$

If  $\gamma$  is of bounded variation with respect to the Minkowskian norm  $\|\cdot\|$ , then

$$(12) \quad \begin{aligned} V_e(\gamma, P) &= \sum_1^n \|\gamma(t_k) - \gamma(t_{k-1})\|_e \\ &= \sum_1^n r(E, u_k) \|\gamma(t_k) - \gamma(t_{k-1})\| \leq R_2 V_m(\gamma, P). \end{aligned}$$

A path is a continuous function  $\gamma : [a, b] \rightarrow \mathbf{R}^n$ .  $\gamma$  is a rectifiable path if and only if  $\gamma$  is a function of bounded variation. Theorem 3 shows that a path is rectifiable with respect to the Euclidean norm if and only if it is rectifiable with respect to the Minkowskian norm.

Let  $P$  be a polygonal path with vertices  $x_0, x_1, x_2, \dots, x_n$ . The Minkowskian length of  $P$  with respect to the unit ball  $E$  is defined by

$$(13) \quad \mu_E(P) = \sum_1^n \|x_i - x_{i-1}\|,$$

where  $\|\cdot\|$  is the Minkowskian norm.

Let  $C$  be a rectifiable path. The Minkowskian length of  $C$  with respect to the unit ball  $E$  is defined by

$$(14) \quad \mu_E(C) = \sup_{P \in \Pi} \mu_E(P)$$

where  $\Pi$  is the set of all polygonal paths inscribed in  $C$ .

Assume now that  $C$  is continuously differentiable. If we let  $ds(C, u)$ ,  $u \in S^{n-1}$ , denote the Euclidean element of arc length at a point where the tangent vector to the curve  $C$  has direction  $u$ , then the Minkowskian element of arc length, denoted by  $ds_m(C, u)$ , is defined by

$$(15) \quad ds_m = \frac{ds_e(C, u)}{r(E, u)}.$$

We can use (13), (14) and (15) to find the following expression for the Minkowskian length of  $C$ , denoted  $l(C)$ .

$$(16) \quad l(C) = \mu_E(C) = \int_C \frac{ds_e(C, u)}{r(E, u)} = \int_C ds_m(C, u).$$

Turning to the case of curves in  $\mathbf{R}^2$ , we let  $ds(C, u) = ds(C, \theta)$ , where  $u = (\cos \theta, \sin \theta)$ . The *self-circumference* of the unit circle  $E$  is the Minkowskian length of  $E$  measured with respect to  $E$  and is given by

$$(17) \quad \mu_E(\partial E) = \int_0^{2\pi} \frac{ds_e(E, \theta)}{r(E, \theta)}.$$

**Results** In this section, we prove Theorem 1 concerning the  $p^{\text{th}}$  mean of curvature in Euclidean spaces and consider generalization of (1) for a closed curve  $C$  in a Minkowski plane.

**Proof of Theorem 1** We can use Hölder's inequality to write

$$(18) \quad K(C) = \int_0^L 1 |\kappa(s)| ds \leq \left( \int_0^L 1 ds \right)^{\frac{1}{q}} \left( \int_0^L |\kappa(s)|^p ds \right)^{\frac{1}{p}}$$

where  $\frac{1}{p} + \frac{1}{q} = 1$ . Hence  $\frac{1}{q} = 1 - \frac{1}{p} = \frac{p-1}{p}$ . Multiplying both sides of (18) by  $R$  and using (2) we obtain

$$(19) \quad L \leq RL^{p-1/p} \left( \int_0^L |\kappa(s)|^p ds \right)^{1/p},$$

giving the desired inequality (3). Equality holds if and only if equality holds in (18) and (2). For equality to hold in (18),  $|\kappa(s)|^p$  has to be constant. The case of equality in (2) implies that equality holds in (3) if and only if  $C$  is a circle of radius  $R$  transversed a certain number of times.

The following theorem is a generalization of (2) in a Minkowski plane. We emphasize that  $K(C)$  is the total Euclidean curvature of a closed curve  $C$ . The proof given here is similar to Chakerian [3] for the inequality (2).

**Theorem 4** Consider a  $C^2$  closed curve  $C$  in a Minkowski space with the unit ball  $E$ . Let  $s$  and  $s_m$  denote Euclidean and Minkowskian arc lengths respectively. Let  $L(C)$  and  $l(C)$  denote Euclidean and Minkowskian lengths of  $C$ . Let  $x = x(s)$ ,  $0 \leq s \leq L(C)$  be a parametric representation of  $C$ . Let "dot" denote differentiation with respect to  $s$ . Then

$$(20) \quad l(C) \leq RK(C) + \int_C \left| \frac{\dot{r}}{r} \right| ds,$$

where  $K(C)$  denotes the total Euclidean curvature of  $C$ ,  $r$  is the radius of  $E$  in the direction of arc length  $ds$ , and  $C$  is constrained to lie in a copy of  $E$  with a dialation factor of  $R$ .

**Proof.** The Minkowskian arc length is given by  $ds_m = \frac{ds}{r}$ . Since  $s$  is Euclidean arc length,  $\dot{x}(s) \cdot \dot{x}(s) = 1$ . Hence we can write  $l(C)$  as follows

$$(21) \quad l(C) = \int_C ds_m = \int_C \frac{ds}{r} = \int_C \frac{1}{r} \dot{x} \cdot \dot{x} ds.$$

Using integration by parts and the triangle inequality, we obtain

$$(22) \quad \begin{aligned} l(C) &= x \cdot \frac{\dot{x}}{r} \Big|_0^{L(C)} - \int_C x \cdot \left( \frac{\dot{x}}{r} \right) ds \\ &= - \int_C x \cdot \left( \frac{\dot{x}}{r} \right) ds \leq \int \|x\|_e \left\| \frac{\ddot{x}r - \dot{r}\dot{x}}{r^2} \right\|_e ds \end{aligned}$$

The fact that  $C$  lies in a copy of  $E$  magnified by dialation factor of  $R$  implies

$$(23) \quad \|x\|_e \leq Rr.$$

Using (22) and (23) we obtain

$$\begin{aligned} l(C) &\leq \int_C \|x\|_e \left\| \frac{\ddot{x}r - \dot{r}\dot{x}}{r^2} \right\|_e ds \\ &\leq \int_C Rr \left\| \frac{\ddot{x}r - \dot{r}\dot{x}}{r^2} \right\|_e ds \\ &\leq \int_C |\ddot{x}| ds + \int_C \left\| \frac{\dot{r}\dot{x}}{r} \right\|_e ds = RK(C) + \int_C \left| \frac{\dot{r}}{r} \right| ds. \end{aligned}$$

In Euclidean spaces the radius of the unit ball in each direction is constant and  $\dot{r} = 0$ . Hence (20) implies (2).

Fenchel's theorem states that the total curvature of a closed space curve  $C$  is greater than or equal to  $2\pi$ . It is equal to  $2\pi$  if and only if  $C$  is a plane convex curve. See Chern [5] for an elementary discussion of Fenchel's theorem. The following theorem shows that the total Minkowskian curvature of a closed convex curve is equal to the self-circumference of the unit circle  $E$ .

**Theorem 5** Let  $C$  be a closed convex curve in a Minkowski plane with the unit circle  $E$ . Then the total Minkowskian curvature of  $C$  is equal to the self-circumference of the unit ball  $E$ .

**Proof.** Let  $\theta$  be the angle between the tangent to  $C$  and the horizontal. Then,

$$\int_C \frac{\kappa(C, \theta)}{\kappa(E, \theta)} ds_m(C, \theta) = \int_C \frac{\kappa(C, \theta)}{\kappa(E, \theta)} \cdot \frac{1}{r(E, \theta)} ds(C, \theta)$$

$$\begin{aligned}
&= \int_C \frac{d\theta}{\kappa(E, \theta)r(E, \theta)} = \int_C \frac{R(E, \theta)d\theta}{r(E, \theta)} \\
&= \int \frac{ds(E, \theta)}{r(E, \theta)} = L(E),
\end{aligned}$$

where we have used the fact that  $ds = \kappa(C, \theta)ds(C, \theta)$  and that  $R(E, \theta)d\theta = ds(E, \theta)$ .

## References

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